

# Intermittency generating $1/f$ noise

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## Abstract

The phrase “ $1/f$  noise” refers to the well-known empirical fact that in many systems at low frequencies the noise spectrum exhibits an approximately  $1/f$  shape. Generating mechanisms leading to  $1/f^\beta$  noise are still an open question. Here we analyze **nonlinear dynamical** systems with invariant subspace having the transverse Lyapunov exponent equal to zero. In particular, we explore nonlinear maps having power-law dependence on the deviation from the invariant subspace. We demonstrate that such maps can generate signals exhibiting  $1/f^\beta$  noise and intermittent behavior. In contrast to known mechanism of  $1/f$  noise involving Pomeau-Manneville type maps, coefficients in the maps we consider are not static, similarly as in the maps describing on-off intermittency. We relate the nonlinear dynamics described by proposed maps to  $1/f$  noise models based on the nonlinear stochastic differential equations.

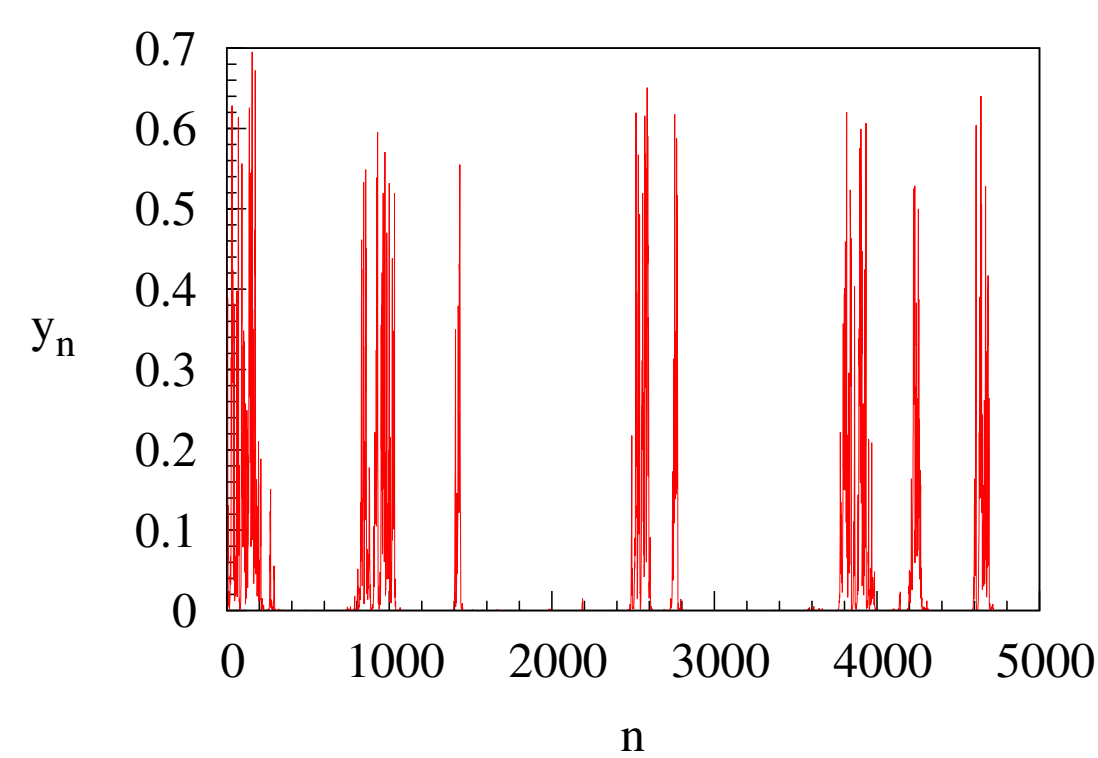
1. J. Ruseckas and B. Kaulakys, Chaos **23**, 023102 (2013).

## Intermittency

**Intermittency** is an apparently random alternation of a signal between a quiescent state and bursts of activity.

Well known models of intermittency:

- Pomeau-Manneville intermittency
- Crisis-induced intermittency
- On-off intermittency



## Model of intermittency with zero transverse Lyapunov exponent

Two-dimensional maps having a **skew product structure**:

$$x_{n+1} = F(x_n), \quad y_{n+1} = G(x_n, y_n)$$

$G(x, 0) = 0$ , thus  $y = 0$  is the **invariant subspace**.

The dynamics  $x_{n+1} = F(x_n)$  restricted to the invariant subspace  $y = 0$  is **chaotic**.

The two terms with the lowest powers in the expansion of the function  $G(x, y)$  in the power series of  $y$  have the form

$$G(x, y) = y + g(x)y^\eta, \quad \eta > 1$$

$\partial G(x, 0)/\partial y = 1$  and, consequently, the **transverse Lyapunov exponent is zero**.

If  $g(x)$  is not constant and can acquire both positive and negative values, the expansion leads to the the map for small values of  $y_n$

$$y_{n+1} = y_n + z_n y_n^\eta, \quad z_n \equiv g(x_n), \quad \eta > 1$$

If the average of the variable  $z_n$  is positive,  $\langle z \rangle > 0$ , and there is a global mechanism of reinjection, the map leads to the **intermittent behavior**.

In order to determine PDF of  $y$  and PSD of the series  $\{y_n\}$ , more terms in the expansion of the function  $G(x, y)$  in the power series of  $y$  are needed

$$y_{n+1} = y_n + z_n y_n^\eta + \gamma y_n^{2\eta-1}$$

Another map:

$$y_{n+1} = (y_n^{1-\eta} + (1-\eta)z_n)^{\frac{1}{1-\eta}}$$

## Approximation by stochastic differential equations

We replace the variable  $z_n$  by a random Gaussian variable having the same average and variance as  $z_n$  and interpret the map as Euler-Marujama approximation of a SDE

$$dy = \sigma^2 \left( \eta - \frac{\nu}{2} + \frac{\eta-1}{2} \left( \frac{y_{\min}}{y} \right)^{\eta-1} \right) y^{2\eta-1} dt + \sigma y^\eta dW$$

Here

$$\sigma = \sqrt{\langle (z - \langle z \rangle)^2 \rangle}, \quad y_{\min} = \left[ \frac{2\langle z \rangle}{(\eta-1)\langle (z - \langle z \rangle)^2 \rangle} \right]^{\frac{1}{\eta-1}}, \quad \nu = 2\eta - \frac{2\gamma}{\langle (z - \langle z \rangle)^2 \rangle}$$

Approximation is valid when

$$y_{\max} \lesssim \langle (z - \langle z \rangle)^2 \rangle^{-\frac{1}{2(\eta-1)}}$$

The condition  $y_{\max}/y_{\min} \gg 1$  is obeyed when

$$\langle (z - \langle z \rangle)^2 \rangle \gg \langle z \rangle^2$$

The SDE leads to the steady state PDF

$$P_0(y) = \frac{(\eta-1)y_{\min}^{\nu-1}}{\Gamma\left(\frac{\nu-1}{\eta-1}\right)y^\nu} \exp\left[-\left(\frac{y_{\min}}{y}\right)^{\eta-1}\right]$$

SDE generates signals with PSD having the form  $S(f) \sim f^{-\beta}$  in a wide range of frequencies with the exponent

$$\beta = 1 + \frac{\nu-3}{2(\eta-1)}$$

Estimation of the range of frequencies where the PSD has the power-law form:

$$\left( \frac{y_{\min}}{y_{\max}} \right)^{2(\eta-1)} \ll 2\pi f \ll 1$$

## Numerical examples

As a mechanism of reinjection we use a reflection at  $y = 0.5$ , leading to the map

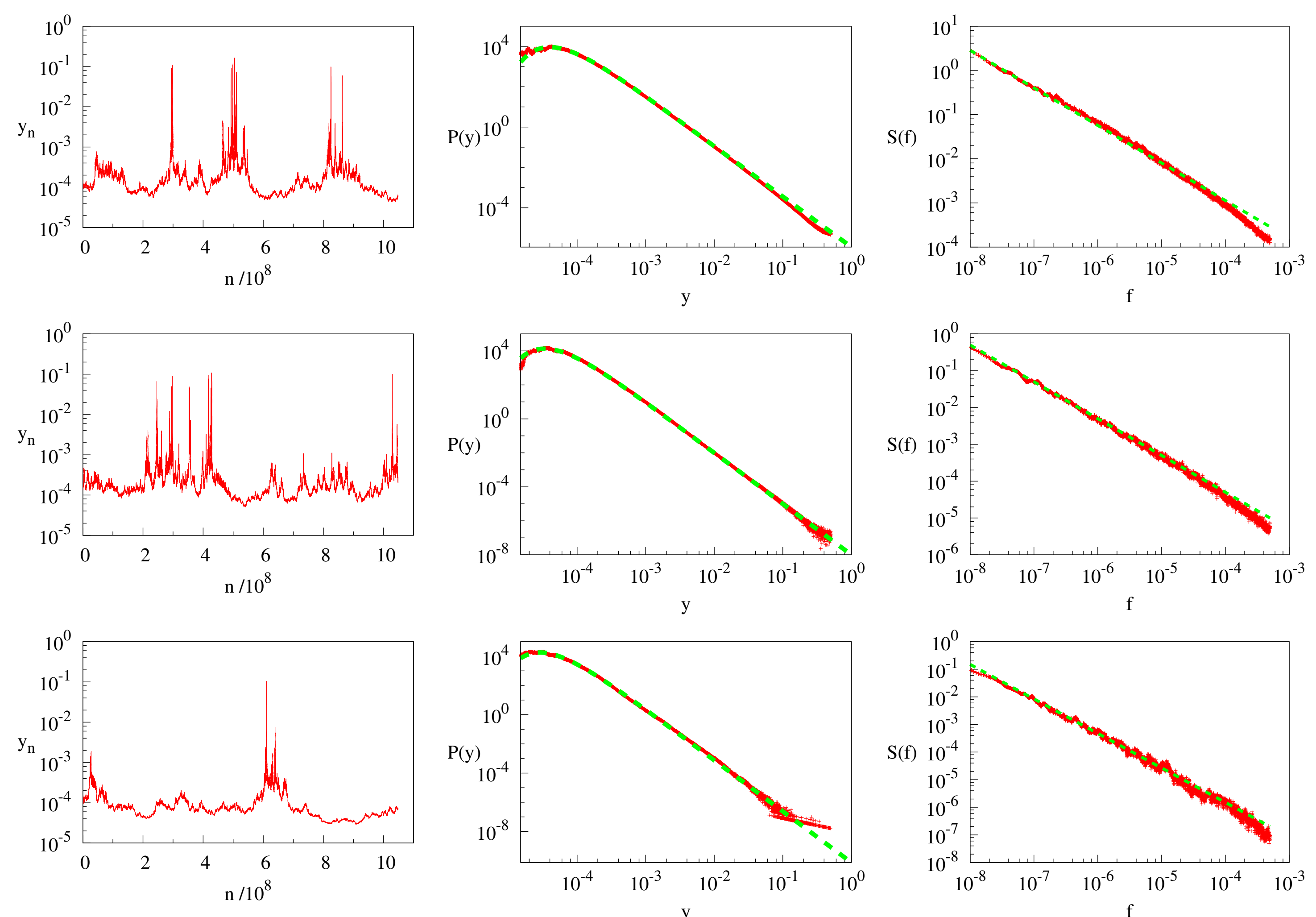
$$y_{n+1} = 0.5 - |y_n + z_n y_n^2 + \gamma y_n^3 - 0.5|$$

As a map  $x_{n+1} = F(x_n)$  in we take the chaotic driving by a tent map

$$x_{n+1} = \begin{cases} 2x_n, & 0 \leq x_n \leq \frac{1}{2} \\ 2 - 2x_n, & \frac{1}{2} \leq x_n \leq 1. \end{cases}$$

The variable  $z_n$  with given average  $\langle z \rangle$  and variance  $\langle (z - \langle z \rangle)^2 \rangle$  can be obtained from  $x_n$  using the equation

$$z_n = \sqrt{\frac{\langle (z - \langle z \rangle)^2 \rangle}{\langle (x - \langle x \rangle)^2 \rangle}} (x_n - \langle x \rangle) + \langle z \rangle$$



$\gamma = 0.75$  (upper row),  $\gamma = 0.5$  (middle row),  $\gamma = 0.25$  (lower row);  $\langle z \rangle = 5 \times 10^{-5}$  and  $\langle (z - \langle z \rangle)^2 \rangle = 1$ .

Another example

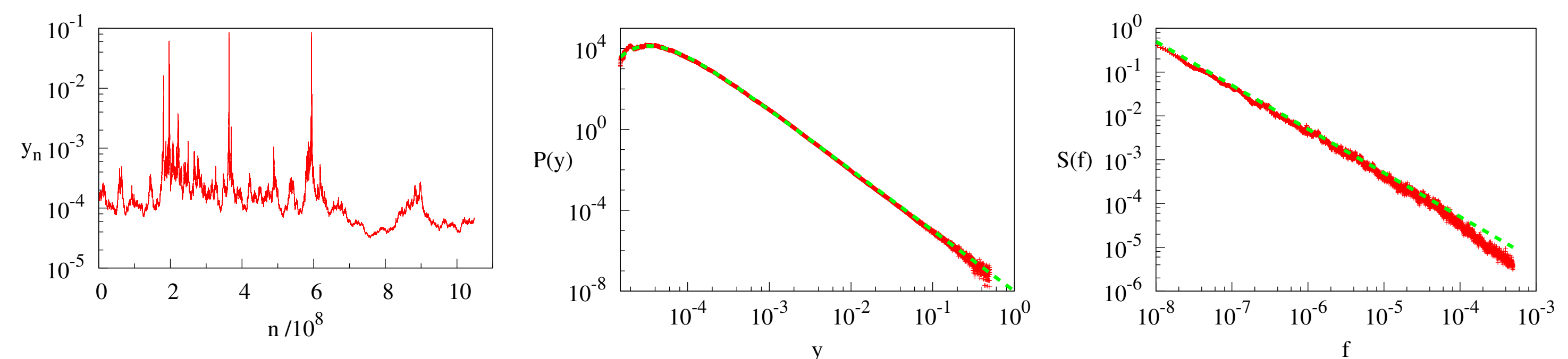
$$y_{n+1} = \begin{cases} y_n - y_n^2 \zeta + 0.5 y_n^3, & 0 \leq x_n \leq p_- \\ 0.5 - |y_n + y_n^2 \zeta + 0.5 y_n^3 - 0.5|, & p_- < x_n \leq 1. \end{cases}$$

where

$$p_{\pm} = \frac{1}{2} \pm \frac{\langle z \rangle}{2\sqrt{\langle (z - \langle z \rangle)^2 \rangle + \langle z \rangle^2}}$$

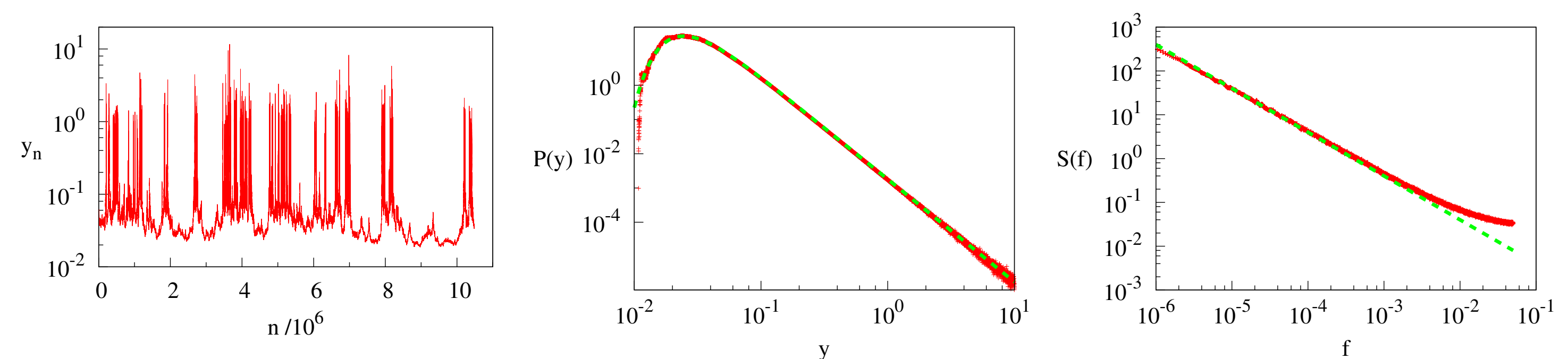
and

$$\zeta = \sqrt{\langle (z - \langle z \rangle)^2 \rangle + \langle z \rangle^2}$$



Third example

$$y_{n+1} = \frac{1}{\sqrt{\left| \frac{1}{y_n^2} - 2z_n \right|}}$$



$\langle z \rangle = 9 \times 10^{-4}$

## Conclusions

- The nonlinear maps having invariant subspace and the expansion in the powers of the deviation from the invariant subspace having the form  $G(x, y) = y + g(x)y^\eta$  can generate signals with  $1/f$  noise.
- In contrast to known mechanism of  $1/f$  noise involving Pomeau-Manneville type maps, the parameter  $z_n$  in the map is **not static**.
- The exponent  $\beta$  in the PSD depends on two parameters  $\eta$  and  $\nu$ , thus  $1/f^\beta$  noise can be obtained for various values of the exponent  $\beta$ .
- The width of the frequency region where the PSD has  $f^{-\beta}$  behavior is limited by the average value of the variable  $z_n$ : this width increases as  $\langle z \rangle$  approaches the threshold value  $\langle z \rangle = 0$ .
- The width of the power-law region in the PSD increases with increasing the difference  $\eta - 1$ .